

## Bachelor's / Master's Thesis (m/w/d)

# Imitation Learning for Dexterous Manipulation: Utilizing Latent Space Representations in Dynamic Movement Primitives

### Problem formulation

Dexterous manipulation in robotics requires learning complex motor skills, which is challenging in open-loop systems due to the lack of feedback mechanisms. Traditional methods, like Dynamic Movement Primitives (DMPs), are effective for encoding movement patterns but often struggle with high-dimensional action spaces. Leveraging latent space representations could address these challenges by simplifying the action space, making it more manageable for open-loop imitation learning.

### Task definition

This thesis will focus on developing an open-loop imitation learning framework that integrates Dynamic Movement Primitives (DMPs) with latent space representations for dexterous manipulation tasks. The research will involve designing and implementing algorithms that encode high-dimensional action spaces into more compact latent representations, improving the system's ability to generalize and execute complex manipulation tasks. The performance of this approach will be evaluated through a series of experiments, measuring the effectiveness in terms of accuracy, robustness, and adaptability to different manipulation scenarios.



### You shall offer

- Solid knowledge base and experience in deep learning, and robotics.
- Coding skills in Python and C++.
- Experience with ROS

### We will offer

- The most state-of-the-art technologies in deep learning and computer vision.
- Working in a lab with a Germany-wide unique Shadow Teleoperation System
- Tight support from supervisors, including a workshop on scientific writing.

**Research area:**  
AI & Robotics

#### Focus:

- Experimental
- Theoretical
- Practical
- Simulation
- Construction (CAD)

#### Study program:

- Maschinenbau
- Mechatronik
- Elektrotechnik
- Informatik
- Informationswirtschaft
- Wirtschaftsingenieurwesen

**Begin:** From now on

If you are interested, please send us an e-mail with your **curriculum vitae** and a current **transcript of records**.

#### Contact person:

Edgar Welte  
Geb. 50.38; Raum 1.15  
Phone: +49 721 608 48645  
edgar.welte@kit.edu

Please note that your data will be treated in accordance with the applicable data protection regulations as part of the application process.